

Practical Foundations of Debugging

Chapter 6

Frame Pointer and Local Variables – Part 2

LocalVariables!main:

```
push    ebp                ; establishing stack frame
mov     ebp,esp            ;
sub     esp,0xd8          ; creating stack frame for locals
push    ebx                ; saving registers that might be used
push    esi                ;   outside
push    edi                ;
lea    edi,[ebp-0xd8]      ; getting lowest address of stack frame
mov     ecx,0x36          ; filling stack frame with 0xCC
mov     eax,0xcccccccc    ;
rep     stosd             ;
mov     dword ptr [ebp-0x8],0x1 ; [a] = 1      ([ebp-0x8])
mov     dword ptr [ebp-0x14],0x1 ; [b] = 1      ([ebp-0x14])
mov     eax,[ebp-0x14]     ; eax := [b]
add     eax,[ebp-0x8]     ; eax := eax + [a]
mov     [ebp-0x14],eax    ; [b] := eax      (b = b + a)
mov     eax,[ebp-0x8]     ; eax := [a]
add     eax,0x1           ; eax := eax + 1
mov     [ebp-0x8],eax     ; [a] := eax      (++a)
mov     eax,[ebp-0x8]     ; eax := [a]
imul   eax,[ebp-0x14]    ; eax := eax * [b]
mov     [ebp-0x14],eax    ; [b] := eax      (b = a * b)
xor     eax,eax           ; eax := 0      (return value)
pop     edi                ; restoring registers
pop     esi                ;
pop     ebx                ;
mov     esp,ebp           ; restoring previous stack pointer
pop     ebp                ; restoring previous stack frame
ret                                ; return 0
```

Comments

- The function that called main may use EDI register (group 1) so it is saved
- Other group 1 registers are saved because without optimization compiler emits standard code (saves all group 1 registers, standard prolog/epilog, etc.)

```
int mainCRTStartup (/*...*/)
{
    // may use group 1 registers (EDI, ...)
    main(/*...*/);
    // may continue use group 1 registers (EDI, ...)
}

int main(/*...*/)
{
    // saves group 1 registers if it uses them (EDI, ...)
    // uses group 1 registers
    // restores group 1 registers (if saved)
}
```

```

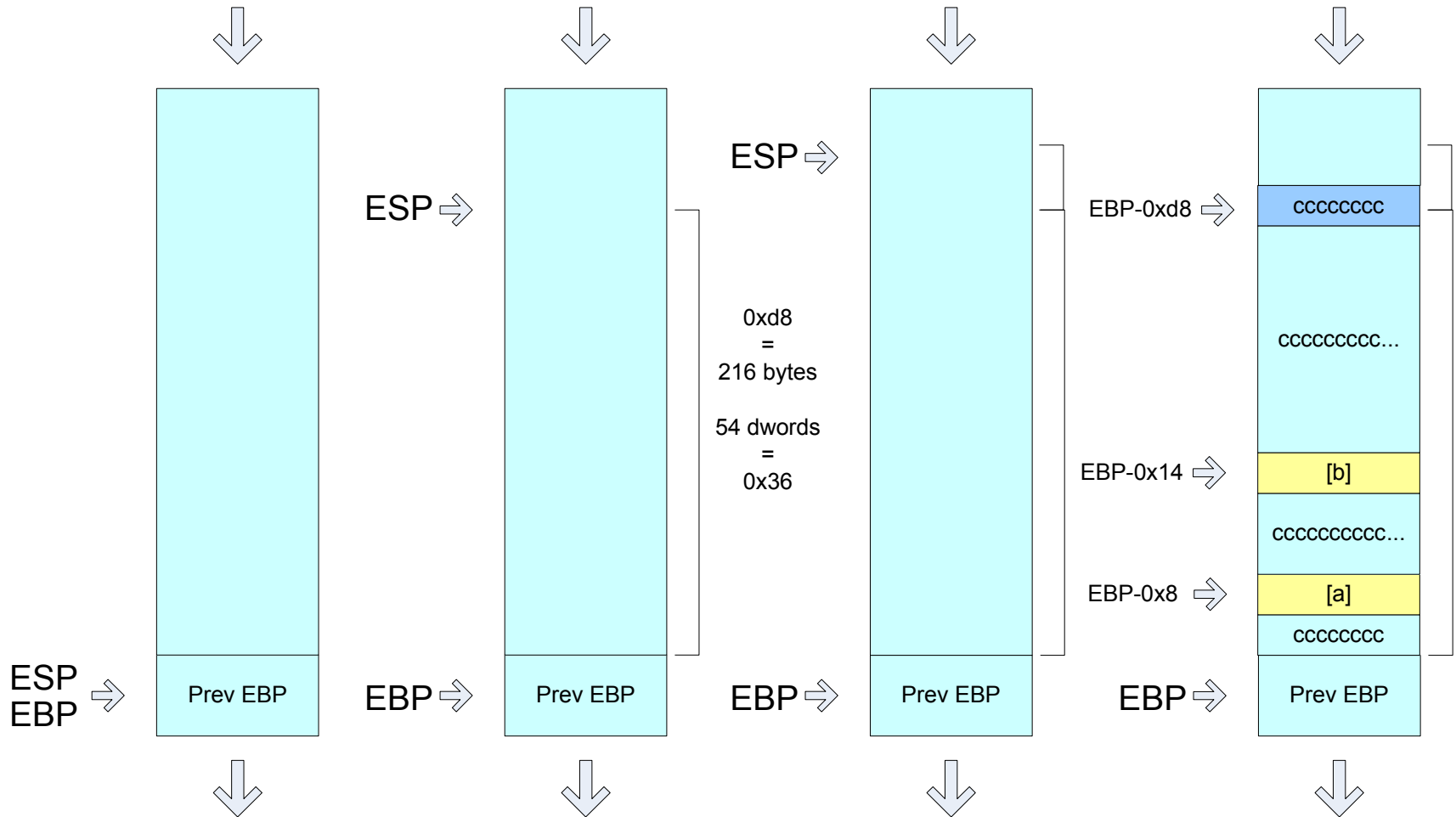
sub    esp,0xd8
push   ebx
push   esi
push   edi
lea    edi,[ebp-0xd8]
mov    ecx,0x36
mov    eax,0xcccccccc
rep    stosd

```

sub esp,0xd8

"Push regs"

lea edi,[ebp-0xd8]



Disassembly for optimized executable (Release configuration)

LocalVariables!main:

```
00401000 33c0          xor     eax,eax
00401002 c3           ret
```

```
int main(int argc, char* argv[])
{
    return 0;
}
```

Where is all the code?

How to preserve the code under optimization?

Modifiers in C and C++

- static

```
static int a, b;
```

- const

```
const int a = 1, b = 1;
```

- volatile

```
volatile int a, b;
```

```
static const volatile a = 1, b = 1;
```

Using volatile modifier

```
int main(int argc, char* argv[])
{
    volatile int a, b;

    a = 1;
    b = 1;

    b = b + a;
    ++a;
    b = a * b;

    return 0;
}
```

FPO

- Frame Pointer omission

Optimization where ESP is used to address local variables and parameters and EBP is used as a general purpose register (like EAX, ECX, etc.)

LocalVariables!main:

```
sub     esp, 0x8           ; allocating stack space for locals
mov     eax, 0x1           ; eax := 1
mov     [esp], eax         ; [a] := eax ([esp])
mov     [esp+0x4], eax     ; [b] := eax ([esp+0x4])
mov     eax, [esp+0x4]    ; eax := [b]
add     eax, [esp]       ; eax := eax + [a]
mov     [esp+0x4], eax   ; [b] := eax (b = b + a)
mov     ecx, [esp]        ; ecx := [a]
inc     ecx                ; ecx += 1
mov     [esp], ecx        ; [a] := ecx (++a)
mov     edx, [esp+0x4]    ; edx := [b]
mov     eax, [esp]       ; eax := [a]
imul   edx, eax         ; edx := edx * eax
mov     [esp+0x4], edx   ; [b] := edx (b = b * a)
xor     eax, eax           ; eax := 0
add     esp, 0x8           ; clearing stack space for locals
ret                                ; return 0
```

What's next?

- Passing parameters to functions
- Accessing function parameters
- “Arithmetical” project with function parameters